

## REMARKS

1. The applicant is sincerely thankful to the examiner for allowing the relevant claims.

2. The applicant has tried his best to amend the original specification as entered with minor linguistic amendments along with the RCE, to incorporate the terminology presented in the allowed claims, without departing from the essence of the basic disclosure made with the help of the drawings at the time of filing. Amendments have been made to the Brief Summary of the Invention and to the Detailed Description of the Invention. Multiple terms used to describe the same elements have been removed with a uniform nomenclature closely related to the terminology used in the Claims. A few non-technical terms used to describe some features of the present invention have been appropriately replaced. Intensive efforts have been made to form a framework in the Brief Summary of the Invention and the Detailed Description of the Invention to logically lead to the allowed Claims. For this purpose, scattered passing references to various functions and features have been bundled in a more concrete and meaningful manner.

3. The applicant respectfully requests the Office to review the amendments made to the specification, following the Office action of 03/16/2005.

4. The applicant can be contacted either by fax 91 11 27315628, telephone 91 11 52455056 or e-mail [anadish@hotmail.com](mailto:anadish@hotmail.com) associated with Cust. No.49300.

Respectfully submitted,

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Attachment: Clean Version of the Specification

## Amendments to the Specification:

Kindly amend the of the Specification as follows:

### BRIEF SUMMARY OF THE INVENTION

This invention fully avoids the earlier problems by increasing the diameter and reducing the number of wheels. ~~[[The]]~~ Ring-like or annulate wheels, two in number, get integrated with the ~~[[shell]]~~ vehicle body of the electric motor ~~[[vehicle,]] vehicle of the present invention~~, doing away with the conventional axle. The ~~[[increased]]~~ large diameter of ~~[[the wheel]]~~ a toroidal electric motor integrated with the annulate wheel, provides more amount of torque at slow speeds without using any gears. The ~~[[shell]]~~ vehicle body of this electric motor vehicle is basically in the form of a cylinder, the circular side of which faces the surface on which the vehicle travels; both the ~~[[end]]~~ ends of the cylinder remain vertical, and these two ~~[[faces]]~~ ends also act as openings. The two annulate wheels ~~in annular form~~ are mounted near the two ~~[[side faces.]]~~ ends, one on either side. The hub of the annulate wheel houses the permanent-magnet toroidal rotor, while the ~~[[circular]]~~ toroidal stator with low-voltage windings is mounted on the basically cylindrical ~~[[shell]]~~ body of the electric motor vehicle, which acts as the axle for both the annulate wheels. In principle, this electric motor vehicle is built inside an enlarged and hollowed out axle. The source of electric power possibly in the form of electrical energy storage devices are kept near that surface of the ~~[[shell]]~~ vehicle body the other side of which always faces the ground; this positioning of the electrical energy storage devices acting as the source of electric power, makes the center of gravity of the electric motor vehicle low and lends stability to the design -- this is possible, because all the electrical energy storage devices like accumulators and superconductor assemblies are heavy. The two ~~[[wheel]]~~ toroidal electric motors one on both the sides ~~either annulate wheels~~, have individual ~~[[inverter]]~~ drives ~~[[also]]~~ controlled by electrical and/or electronic processing units for running the two toroidal electric motors and also effecting regenerative braking when needed. Steering is accomplished by differential rotation of the two ~~[[giant]]~~ annulate wheels. An ~~electrical or wireless~~ electronic communication link between two or more such vehicles would

enable all-thus-linked vehicles to travel ~~[[in tandem,]]~~ as a train of identical vehicles, main steering being done by the vehicle on the front; this will simulate the present-day multi-wheel modes of transport, with the ease of detachability and flexibility.

Thus, this invention avoids the use of gears, a mechanical steering, suspensions and pneumatic tires; it has a much greater ~~[[torque-generation]]~~ torque generation, compared to other motor-wheel designs. The rolling coefficient of friction is ~~[[low,]]~~ small, because the chord-versus-the-wheel-circumference ratio at the ground contact is low due to the increased effective diameter of the annulate wheel (which is more like a hub). This invention helps to increase the effective traveling range of an electrical vehicle with this novel structural design.~~[[design philosophy.]]~~ As the source of electric power is electrical-energy accumulators are placed at a level close to the ground, replacing them is easier compared to ~~[[the]]~~ many existing ~~[[design]]~~ designs of electric motor vehicles. With efficiency, simplicity and flexibility, this invention may be the harbinger of the imminent advent of a truly electrical motor vehicle.

The characteristic features of the invention are set forth, in particular, in the appended claims; however, the following description in detail in context to the drawings facilitates a greater understanding of the unique concepts this invention embodies. But this should be taken as illustrative, rather than restricting the scope of the ideas set forth in the section of claims. The principles and features of this invention may be utilized in applications outwardly dissimilar but in essence not departing from the scope of this invention.

## DETAILED DESCRIPTION OF THE INVENTION

FIG.1 shows the side view of the vehicle. The total height of the vehicle is nearly 50 inches. In this present form, it is designed to accommodate two persons with some luggage space at the back. The seats are marked S. The ~~[[batteries]]~~ batteries, the source of electric power in this embodiment of the present invention, are placed below ~~[[the]]~~ seats S, in battery enclosure BAT (~~FIG.1 and FIG.2~~). (FIG.1, FIG.2 and FIG.3). There is a provision ~~[[to keep]]~~ for keeping four lead acid batteries of [[4 Nos. of ordinary]] 200AH, 12V [[lead acid batteries.]] rating. The total weight of the batteries is 240 kgs. The position of battery enclosure BAT keeps the center of gravity of the vehicle very low; this, coupled with the eccentric loading on the vehicle, provides stability to the vehicle, in spite of its having only two parallel annulate wheels. The batteries could be placed in two arrangements. One is side by side, so that the batteries could be taken out from the direction of BP in FIG.1. Battery protector BP is made of material having good impact ~~[[strength]]~~ strength, capable of withstanding shock from the rear. A hinged joint at axis marked HN (FIG.1), allows battery protector BP to swivel down and rest on the ground on its edge. Thus facilitating the removal or insertion of the batteries from the rear. The batteries could also be arranged in a transverse manner, as shown in FIG. 2. In this case, the batteries have to be accessed from the ~~[[side]]~~ doors or the passenger openings on both the sides of the vehicle (FIG.1). As the batteries, in this arrangement, are placed in the cavity behind ~~[[direct-drive]]~~ toroidal electric motor M (FIG.1 and FIG.2), with the toroidal stator of [[direct-drive]] toroidal electric motor M obstructing (indicated by OBS in FIG.1) the bottom corners of the batteries, it is not possible to simply slide the batteries ~~[[out]]~~ out, one by one. The backrests have to fold down on the seats, while the seats ~~[[having]]~~ have an arrangement to get lifted slightly to make sufficient clearance for the batteries; ~~[[then]]~~ a pneumatically operated rubber bag placed below the batteries as a collapsed cushion is inflated to get the batteries lifted enough to be able to slide them out. This arrangement is slightly more complicated than the earlier-described battery-removal procedure; but it makes the vehicle ~~[[shell]]~~ body stronger by integrating battery protector BP with the ~~[[shell,]]~~ vehicle body, ~~[[thus]]~~ reducing the number of joints in the vehicle ~~[[shell.]]~~ body. The top and front sides of ~~[[the]]~~ battery enclosure BAT have to be strong and be fully linked ~~[[with]]~~ to the structure of the ~~[[shell]]~~ vehicle body and, at the extremities, ~~[[with direct-drive rim]]~~ to toroidal electric motors [[M:]] M. So that, in case of an accidental collision, the batteries do not damage the

legs of the occupants of the ~~[[seats.]]~~ seats, the passengers. The linking of the two ends of the ~~[[shell]]~~ vehicle body with the ~~[[body element]]~~ elements of ~~[[the]]~~ battery enclosure BAT also increases the overall strength of the vehicle ~~[[shell.]]~~ body.

The ~~[[back rests]]~~ backrests of ~~[[the]]~~ seats S (FIG.1, FIG.2 and FIG.3) could be adjusted somewhat to obtain different reclining angles. In FIG.1, the areas marked B both on the front and ~~[[rear both]]~~ rear indicate the ~~[[light-weight]]~~ lightweight plastic bumpers. They have an elevated face (FIG.2) marked EL to offer a limited length of their full face in case of a collision, to avoid the shock getting transferred on to the annulate wheels and distorting them. ~~[[Though,]]~~ Although, the ridged sheet-metal rims of the annulate wheels (FIG.2) offer a degree of flexibility and resilience necessary to withstand the rough rides. The tires are ~~[[huge]]~~ large in diameter (nearly 50 inches), but are ~~[[very thin (just an inch).]]~~ quite narrow. ~~This reduces the rolling friction; avoids the use of any kind of suspension or shock absorbers;~~  
The application of this kind of tires, avoids making use of any kind of suspension or shock absorbers, reduces the rolling friction between the tires and road surface R (FIG.1 and FIG.3), and opens the possibility of using a solid low-cost rubber ~~[[tire (FIG.3, TIRE).]]~~ tire, shown as TIRE in FIG.3.

The passenger opening or the doors on both the sides of the vehicle hinge at the axis near the ~~[[back rest]]~~ backrests of the seats (AA in FIG.1); the height of the ~~[[doors]]~~ passenger openings is nearly 3 feet. The possible sliding glass portions of the window is marked WN in FIG.1. The small area on the right-hand side of vertical axis AA (FIG.1) is immovable and is fixed to the vehicle ~~[[shell.]]~~ body. The passenger opening or the doors are fully encircled by the fully toroidal rotors. This arrangement utilizes the area of the inner circle of the outer toroidal form of toroidal electric motor M (shown clearly in FIG.1).

The windscreen vertically, in a circular fashion, spans points WW (FIG.1). The ~~[[head lamps]]~~ headlamps are placed in niche HL (FIG.1) -- shown more clearly in FIG.3. In order to conserve power, use is made of ~~[[2 Nos. of]]~~ two 20W fluorescent tubes driven by high frequency drivers. The right and left turn indicators are marked TIL in FIG.3. The two fluorescent tubes with suitable cylindrical reflectors produce high and low beams; the Fresnel lenses in the path of light help to further focus the light beam.

On the ~~[[rear-side end]]~~ rear-end side of the electric motor vehicle, there is a boot space, boot hatch door BH in FIG.1. There are two locations for keeping the ~~[[various]]~~ electrical and/or electronic ~~[[controllers.]]~~ connecting and processing units. One is the rear side of the seat ~~[[back rests;]]~~ backrests; the other is the place marked E in FIG.1. The traction, steering, braking and communication with the ~~[[virtually-linked]]~~ remainder of the linked train of identical or similar vehicles ~~[[in tandem: all]]~~ are accomplished by using the speed data of the toroidal electric motors, with the help of ~~[[this controller and drives.]]~~ the electrical and/or electronic connecting and processing units. There are two separate drives for the two toroidal, permanent-magnet ac motors working as direct-driving rim ~~[[motors.]]~~ motors shown as ~~[[direct-driving]]~~ toroidal electric motor M (FIG.1, FIG.2 and FIG.3). By altering the rpm of individual toroidal electric ~~[[motors,]]~~ motors M, steering of the vehicle is achieved. By stopping one toroidal electric motor M entirely, the moving annulate wheel of the vehicle of the present invention draws a circle on the ground, the center of which is the point where the non-rotating annulate wheel rests on the ground; this capability makes the turning radius very small, equal to the distance between the ~~centers of the two~~ tires, ~~tires on the either side~~. Dynamic regenerative braking is also effected by the two drives; and is very effective, owing to the ~~[[huge]]~~ large diameter of the motor. The toroidal stator is either annular or semi-annular in axial profile, is wound for ~~[[24V.]]~~ 24V dc, and is epoxy encapsulated. The toroidal rotor consists of small ferrite magnets arranged on the rotating ~~[[rim.]]~~ hub. Instead of using ferrite or other permanent magnets for forming the fully toroidal rotor, use can also be made of electromagnetic pole pieces for constructing the fully toroidal rotor. The bearing of ~~[[the]]~~ toroidal electric motor M is on the inside of the walls of the ~~[[wine-glass-like]]~~ wine glass shape (WG in FIG.2), adjacent to ~~[[direct drive]]~~ toroidal electric motor M in FIG.2. At the parting lines of the toroidal rotor and the toroidal stator, to protect the bearing from dirt, there are thin annular rubber curtains, against which there is an optional positive air pressure from the inside of the toroidal stator -- worked up by a small centrifugal ~~[[fan]]~~ pump which sucks filtered air from the inside of the vehicle and pushes it out through the leakage between the line of contact between the rubber curtain and the hub and the axle to prevent the entry of dust, dirt and water at low pressure heads.

In case of the failure of the switching devices of one or both the drives, there is a provision for two parallel stopping drives which otherwise work as regenerative brakes to first charge two capacitors from the regenerative braking power and then to step up the capacitor voltage

with a switching converter ~~[[and then]]~~ to charge the batteries. To act as parking brakes, on points marked as (FIG.1) PBR, there are two small dc motors with integral gears driving two threaded shafts which in turn move threaded sliding blocks lined on their heads with brake material. Application of this braking arrangement involves the rotation of the geared dc motors in the positive direction in order to move the braking sliders towards the toroidal rotor's magnetic face. When the brake linings press against the toroidal rotor face, due to the ~~[[enormous]]~~ large diameter of the toroidal rotor, the braking effectiveness is very good. In order to release this parking brake, the direction of motor rotation is ~~[[reversed]]~~ reversed, by reversing the connections to the small dc motors electrically. This braking is indispensable while parking, as there are no gears in this ~~[[vehicle]]~~ electric motor vehicle, and injecting a dc voltage in the toroidal rotor to achieve electromagnetic braking would unnecessarily drain the ~~[[battery.]]~~ batteries.

Steering, speed and braking are manually controlled by operating a wired or cordless ~~[[joystick;]]~~ joystick which is connected to the electrical and/or electronic connecting and processing units; the driver may sit at any location in the vehicle. Ground clearance even on an inclined surface is adequately demonstrated with reference to the line marked ~~[[INCL.]]~~ INCL in FIG.1. ~~It is also noticeably clear in FIG.3, just above the road surface marked R.~~

~~The number of batteries could be made just two, to make the vehicle lighter and go faster, with the traveling distance getting halved. By making the driver sit in a more crouched manner, the diameter as well as the breadth of the vehicle could be reduced to produce a [[midget-size]] small vehicle, [[unlike]] quite like the conventional [[bikes:]] bikes; but a stable [[A stable]] vehicle primarily intended for a single passenger. suitable for single occupancy, protecting the occupant from the vagaries of the weather.~~

Dynamic towing is achieved by attaching one or more identical or similar vehicles behind or along the sides of ~~[[the]]~~ a pilot vehicle. ~~An electronic~~ Electronic communication ~~[[link]]~~ links between the vehicles permits the driver of the pilot vehicle to safely steer this train of identical vehicles; [[thus effecting]] and puts into effect the concept of splitting of a conventional four-wheel vehicle, or joining up, as and when required. The vehicles following the pilot vehicle have a user-defined degree of maneuverability. [[The]] In another version of the present invention, the addition of a towing link in the form of hooks or hitches on the

[[backside]] rear side of this electric motor vehicle will enable it to [[work]] function as a traction vehicle inside factories. Unlike conventional three-wheeled electrical traction vehicles, the driver sits inside a well-defined and protected space, though the overall size of the vehicle is smaller compared to its existing counterparts.

The peculiarities of this electric motor vehicle design make it very stable in dynamic performance. While applying brakes, the vehicle [[shell]] body (in FIG.1) tends to rotate along with the annulate wheels, but the heavy battery compartment keeps moving forward, [[thus]] canceling [[out]] the likely anti-clockwise swing of the vehicle body. [[shell anti-clockwise.]] The position of the occupants of the vehicle always remains gravitationally the same, reducing, possibly, stress while traveling over [[inclines,]] inclines (INCL in FIG.1).

The batteries, even if replaced by fuel cells or superconductor assemblies, always have one common feature -- weight. The weight of the source of electric power in the form of electrical energy storage or generating units could not [[possibly]] probably be reduced in near future. And in this design this concentration of weight lends itself remarkably well to the effective functioning of this electric motor vehicle.

To improve the dimensional stability of the [[shell,]] vehicle body, ridges are formed on the sheet-metal [[shell]] vehicle body, just at the place where the [[shell]] vehicle body forms a neck to accommodate [[the wheel]] toroidal electric [[motor,]] motor M, shown in FIG.2 and FIG.3 (RIDGES).

In a [[midget-sized single-seater]] small, preferably single-seating version of the present vehicle, the [[back rest]] backrest is in a foldable form; two such [[back rests]] backrests linked to both the sitting edges of the driver seat make it possible for a passenger to sit inside the vehicle facing any of the two ends -- conventional front or rear -- and drive, as there are no mechanical linkages for driving this vehicle; and the joystick controller could be operated [[in]] from any position.